

The equivalence of schemata with some feedbacks

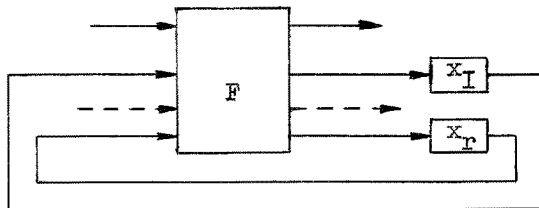
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I. Introduction.

We study the schemata, their elements being automata. The definition of scheme of automata is given in [1]. In our work an automata means an initial Mealy automata.

I.1. Simple schemata. Every scheme of automata with r feedbacks may be represented in a form of so called simple scheme (see picture).



An automata F will be referred to as a basic automata of a simple scheme, automata x_1, \dots, x_r - as feedback automata.

For convenience we'll consider only such schemata in which all feedback automata have the same input alphabets and the same output alphabets.

I.2. GM-automata. Definition. Let F be an automata with $r+1$ input and $r+1$ output, inputs and outputs of F are enumerated from 0 to r .

An automata F is a generalized Moore automata (GM-automata) if output symbols in all output channels except zero output channel depend only on the input symbol in zero channel and on the state of automata F . I.e. if F - GM-automata with the input alphabet $\sum_0 \times \Sigma^r$ and the output alphabet $T_0 \times T^r$, the set of states Q and the output function $\psi: Q \times (\sum_0 \times \Sigma^r) \rightarrow T_0 \times T^r$, then

$$\forall q \in Q \forall \pi, \rho \in \sum_0 \times \Sigma^r \forall i \in \{1, \dots, r\} (\pi^0 = \rho^0 \supset \psi^i(q, \pi) = \psi^i(q, \rho)).$$

Mark, that the output symbol in zero output channel of GM-automata may depend on the input symbols in all input channels.

A number r is referred to as a dimension of a GM-automata F below. Dimension of GM-automata F is denoted $\dim F$.

I.3. S-equivalence of GM-automata. It's evident, that if an automata F is a GM-automata with the input alphabet $\sum_0 \times \Sigma^r$ and the output alphabet $T_0 \times T^r$, then for any automata x_1, \dots, x_r with the input alphabet T and the output alphabet Σ , the simple scheme with

the basic automata F and the feedback automata x_1, \dots, x_r is defined correctly.

An automata given by this scheme we'll denote as $S(F, x_1, \dots, x_r)$.

An input alphabet of $S(F, x_1, \dots, x_r)$ is Σ_0 and an output alphabet is T_0 .

Definition. Two r -dimensional GM-automata F and G are s-equivalent if for any automata x_1, \dots, x_r the automata $S(F, x_1, \dots, x_r)$ and $S(G, x_1, \dots, x_r)$ are equivalent.

Definition. A word v and automata x_1, \dots, x_r s-distinguish r -dimensional GM-automata F and G if the output words of automata $S(F, x_1, \dots, x_r)$ and $S(G, x_1, \dots, x_r)$ on the word v are different.

I.4. List of results. We give the algorithm which constructs a GM-automata with minimal number of states. This minimal GM-automata is unique in some exact sense (Theorems I,2).

Also we give an upper bound of a length of the experiment which determines s -equivalence of given GM-automata, i.e. a bound for the length of such word v , that v and some automata x_1, \dots, x_r s -distinguish given GM-automata (Theorem 5). This upper bound can't be improved essentially (Theorem 6).

We generalise the concept of s -equivalence to the case of schemata with nonequal number of feedbacks and prove theorems analogous to above theorems (Theorems 3,4).

A problem of s -equivalence of two GM-automata is solvable because of above bounds.

2. The minimization of GM-automata.

Designation $F = \langle \Gamma, Q, \Delta, q_0, \varphi, \psi \rangle$ means F is the automata with the input alphabet Γ , the set of states Q , the output alphabet Δ , the initial state q_0 , the transition function $\varphi: Q \times \Gamma \rightarrow Q$, and the output function $\psi: Q \times \Gamma \rightarrow \Delta$.

2.1. The normal form of the GM-automata. Definition. Let F be a GM-automata with the input alphabet $\Sigma_0 \times \Sigma^r$ and the output alphabet $T_0 \times T^r$, q is a state of F and $\sigma_0 \in \Sigma_0$.

A feedback channel i ($i \in \{1, \dots, r\}$) is named q, σ_0 -essential if there exist a word $v \in \Sigma_0 \cdot \Sigma_0^*$ and automata $X_1, \dots, X_{i-1}, X_{i+1}, \dots, Y, Z$ such that the output words of the automata $S(F, X_1, \dots, X_{i-1}, Y, X_{i+1}, \dots, X_r)$ and $S(F, X_1, \dots, X_{i-1}, Z, X_{i+1}, \dots, X_r)$ on the word v are different.

Let's fix the letter $\theta \in T$.

Definition. The normal form of the GM-automata $F = \langle \Sigma_0 \times \Sigma^r, Q, T_0 \times T^r, q_0, \varphi, \psi \rangle$ is the GM-automata $G = \langle \Sigma_0 \times \Sigma^r, Q, T_0 \times T^r, q_0, \varphi, \mu \rangle$, where $\mu^o(q, \sigma) = \psi^o(q, \sigma)$, and for every $i \in \{1, \dots, r\}$

$$\mu^{i(q, \sigma)} = \begin{cases} \psi^i(q, \sigma), & \text{if } i \text{ is } q, \sigma^0\text{-essential channel} \\ \theta & \text{in opposite case} \end{cases}$$

Evidently, the normal form of any GM-automate is a GM-automate.

2.2. Permutations of channels. Definition I. Let $F = \langle \Sigma_0 \times \Sigma^r, Q, T_0 \times T^r, q_0, \varphi, \psi \rangle$ and $G = \langle \Sigma_0 \times \Sigma^r, Q, T_0 \times T^r, q_0, \lambda, \mu \rangle$ be the GM-automata and (i_1, \dots, i_r) is a permutation.

We say that GM-automate G is obtained from GM-automate F by permutation (i_1, \dots, i_r) if for every state $q \in Q$, letters $\sigma_0, \sigma_1, \dots, \sigma_r \in \Sigma_0 \times \Sigma^r$ and $j \in \{1, \dots, r\}$.

$$\begin{aligned} \lambda(q, \sigma_0, \sigma_1, \dots, \sigma_r) &= \varphi(q, \sigma_0, \sigma_{i_1}, \dots, \sigma_{i_r}) \\ \mu^0(q, \sigma_0, \sigma_1, \dots, \sigma_r) &= \psi^0(q, \sigma_0, \sigma_{i_1}, \dots, \sigma_{i_r}) \\ \mu^{ij}(q, \sigma_0, \sigma_1, \dots, \sigma_r) &= \psi^j(q, \sigma_0, \sigma_{i_1}, \dots, \sigma_{i_r}) \end{aligned}$$

2. GM-automata F and G are p-equivalent (p-isomorphic) if F is equivalent (isomorphic) to some automate which may be obtained from G by some permutation.

2.3. The minimization theorem. We'll say 'G is a minimal GM-automate for GM-automate F' instead 'G is a GM-automate with smallest number of states which is equivalent to F'.

Lemma I. GM-automata F and G are s-equivalent if and only if their normal forms are p-equivalent.

Using lemma I we can prove the next theorem.

Theorem I. Let F be a finite GM-automate.

1. The reduced automate which is equivalent to normal form of GM-automate F is a minimal GM-automate for F.

2. If G and H are minimal GM-automata for F, then normal forms of G and H are p-equivalent.

Lemma 2. There exist an algorithm which constructs the normal form of the given GM-automate.

Theorem 2. There exist an algorithm of constructing minimal GM-automate for the given finite GM-automate F.

The last theorem immediately follows from theorem I and lemma 2 and from ability to construct reduced automate which is equivalent to the given finite automate.

3. Enriched GM-automata

3.1. Maps connected with GM-automata. Designation. Let Γ and Δ be the finite alphabets. The set of all automata with input alphabet Γ and output alphabet Δ will be denoted $k(\Gamma, \Delta)$.

Every GM-automate $F \in k(\Sigma_0 \times \Sigma^r, T_0 \times T^r)$ gives a map $S_F: k(T, \Sigma)^r \rightarrow k(\Sigma_0, T_0)$ which maps ordered set x_1, \dots, x_r into aut-

omate $S(F, X_I, \dots, X_r)$.

Evidently, GM-automata F and G are s -equivalent if and only if maps S_F and S_G are equal.

3.2. Enriched GM-automata and s -distinguishing of them. A map $S_F: \langle x_I, \dots, x_r \rangle \rightarrow S(F, X_I, \dots, X_r)$ may be considered as a function of only part of variables x_I, \dots, x_r treating other variables as parameters.

Except that we may don't want differ maps connected with p -equivalent GM-automata. So we get the next definitions.

Definition. Enriched GM-automate (EGM-automate) is a couple F, f where F is a GM-automate and f is a partial function from $\{I, \dots, \dim F\}$ to the set of integers (about designation $\dim F$, see I.2).

The dimension of EGM-automate $\langle F, f \rangle$ is dimension of GM-automate F . Let F, f and G, g be EGM-automata, $\dim \langle F, f \rangle = r$, $\dim G, g = d$

We'll say that the word v and two sequences of automata x_I, \dots, x_r y_I, \dots, y_d s -distinguish EGM-automata $\langle F, f \rangle$ and $\langle G, g \rangle$ if (i) for all $i \in \{I, \dots, r\}$ and $j \in \{I, \dots, d\}$ if $f(i)$ and $g(j)$ are defined and $f(i) = g(j)$, then x_i is equivalent to y_j ; (ii) output words of automata $S(F, X_I, \dots, X_r)$ and $S(G, Y_I, \dots, Y_d)$ on the word v are different.

Definition. EGM-automata $\langle F, f \rangle$ and $\langle G, g \rangle$ are named s -distinguishable if there exist the word v and the sequences x_I, \dots, x_r , y_I, \dots, y_d which s -distinguish $\langle F, f \rangle$ and $\langle G, g \rangle$.

A connection between s -distinguishing of GM-automata and EGM-automata gives the next lemma.

Lemma 3. Let F and G be the GM-automata, $\dim F = \dim G = r$, and E_r is an identical function with domain $\{I, \dots, r\}$. The word v and automata x_I, \dots, x_r s -distinguish GM-automata F and G if and only if the word v and the sequences of automata x_I, \dots, x_r , x_1, \dots, x_r s -distinguish EGM-automata $\langle F, E_r \rangle$ and $\langle G, E_r \rangle$.

3.3. The minimization of EGM-automata. The definitions of normal form of EGM-automate and p -equivalence of EGM-automata are analogous to the correspondent definitions for GM-automata and we won't cite them here.

Definition. EGM-automate $\langle G, g \rangle$ is the minimal EGM-automate for EGM-automate $\langle F, f \rangle$ if $\langle G, g \rangle$ is the EGM-automate with smallest number of states and with smallest dimension, which is not s -distinguishable from $\langle F, f \rangle$.

Theorem 3. Let $\langle F, f \rangle$ be the r -dimensional EGM-automate and $f(i)$ is defined for every $i \in \{I, \dots, r\}$.

I. There exist an algorithm which constructs the minimal EGM-aut-

omate for $\langle F, f \rangle$.

2. If $\langle G, g \rangle$ and $\langle H, h \rangle$ are the minimal EGM-automata for $\langle F, f \rangle$, then the normal forms of $\langle G, g \rangle$ and $\langle H, h \rangle$ are p-equivalent.

4. Length of experiments with schemata

4.1. The main theorems.

Theorem 4. Let $\langle F, f \rangle$ and $\langle G, g \rangle$ be the s-distinguishable EGM-automata, F and G have no more than n states. Let t be a number of such integers i that $f(i) = g(j)$ for some j.

There exist the word v and two sequences of automata x_1, \dots, x_r , y_1, \dots, y_d such that

- (i) v, x_1, \dots, x_r , y_1, \dots, y_d s-distinguish $\langle F, f \rangle$ and $\langle G, g \rangle$;
- (ii) a length of v is no more than $(t+2) \cdot n$.

Next theorem 5 is a simple corollary from lemma 3 and theorem 4.

Theorem 5. Let F and G be r-dimensional non s-equivalent GM-automata, F and G have no more than n states.

There exist such word v and automata x_1, \dots, x_r that

- (i) v and x_1, \dots, x_r s-distinguish F and G,
- (ii) a length of v is no more than $(r+2) \cdot n$.

4.2. Given upper bounds are asymptotically exact.

Theorem 6. There exist non s-equivalent GM-automata F and G such that

- (i) $\dim F = \dim G = r$,
- (ii) F and G have no more than n states,
- (iii) For any word v and any automata x_1, \dots, x_r if the length of v is less than $(n-r+1) \cdot (r+2) - 1$, then v, x_1, \dots, x_r don't s-distinguish F and G.

Literature

I. Kobrinsky, Trakhtenbrot. Introduction to the finite automata theory, Moscow, 1962.